

11 Systems of differential equations

11.1 Basics of systems of differential equations

Convert to an equivalent first order system.

$$y'' + 17y' + 3y = e^x$$

$$\begin{cases} x_1 = y \\ x_2 = y' \end{cases} \Rightarrow \begin{cases} x_2' = y'' \\ x_1' = x_2 \end{cases}$$

$$y'' + 17y' + 3y = e^x$$

$$x_2' + 17x_2 + 3x_1 = e^x$$

$$\hookrightarrow x_2' = -17x_2 - 3x_1 + e^x$$

$$\begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -3 & -17 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ e^x \end{bmatrix}$$

Convert to an equivalent first order system.

$$x'' = x + y$$

$$y'' = 2x - 3y$$

$$x'' = x + y$$

$$y'' = 2x - 3y$$

$$x_1 = x \quad x_3 = y$$

$$x_2 = x' \quad x_4 = y'$$

$$\therefore x_2 = x_1' \quad \therefore x_4 = x_3'$$

$$x_2' = x_1 + x_3$$

$$x_4' = 2x_1 - 3x_3$$

$$\begin{bmatrix} x_1' \\ x_2' \\ x_3' \\ x_4' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 2 & 0 & -3 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

Rewrite the following first-order system into a second-order equation for $x(t)$.

$$x' = 3x + 2y$$

$$y' = x - y$$

$$\begin{aligned} x' &= 3x + 2y \Rightarrow y = \frac{1}{2}x' - \frac{3}{2}x \\ x'' &= 3x' + 2y' \Rightarrow y' = \frac{1}{2}x'' - \frac{3}{2}x' \\ y' &= x - y \end{aligned}$$

$$\frac{1}{2}x'' - \frac{3}{2}x' = x - \left(\frac{1}{2}x' - \frac{3}{2}x\right)$$

$$\frac{1}{2}x'' - x' - \frac{5}{2}x = 0$$

11.2 Constant coefficient systems

Find the general and specific solutions of the following system.

$$\begin{aligned}x' &= 2x - 3y \\ y' &= -3x + 10y\end{aligned}$$

$$x(0) = 1 \quad y(0) = 4$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ -3 & 10 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$A - \lambda I = \begin{vmatrix} 2-\lambda & -3 \\ -3 & 10-\lambda \end{vmatrix} = (\lambda^2 - 12\lambda + 11) \\ = (\lambda - 11)(\lambda - 1) \\ \lambda = 1, 11$$

$$\begin{array}{c} \lambda = 1 \\ \begin{bmatrix} 3 \\ 1 \end{bmatrix} \end{array} \quad \begin{array}{c} \lambda = 11 \\ \begin{bmatrix} 1 \\ -3 \end{bmatrix} \end{array}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = c_1 e^{1t} \begin{bmatrix} 3 \\ 1 \end{bmatrix} + c_2 e^{11t} \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

$$\begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 4 \end{bmatrix} = c_1 e^0 \begin{bmatrix} 3 \\ 1 \end{bmatrix} + c_2 e^0 \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

$$-1 = 3c_1 + c_2$$

$$4 = c_1 - 3c_2$$

$$c_1 = \frac{1}{10} \quad c_2 = -\frac{13}{10}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{10} e^t \begin{bmatrix} 3 \\ 1 \end{bmatrix} - \frac{13}{10} e^{11t} \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

Find the general and specific solutions of the following equation.

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \quad \begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

$$A - \lambda I = \begin{vmatrix} -\lambda & 1 \\ -1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0 \\ \lambda = \pm i$$

$$\begin{array}{c} \lambda = i \\ A - iI = \begin{bmatrix} -i & 1 \\ 1 & -i \end{bmatrix} \end{array}$$

$$\begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\text{Plug into } e^{at} (\cos(bt) + i \sin(bt)) \begin{bmatrix} v \end{bmatrix}$$

$$= e^{0t} (\cos(t) + i \sin(t)) \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$= \begin{bmatrix} \cos(t) + i \sin(t) \\ i(\cos(t) + i \sin(t)) \end{bmatrix}$$

$$= \begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix} + i \begin{bmatrix} \sin(t) \\ \cos(t) \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = c_1 \begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix} + c_2 \begin{bmatrix} \sin(t) \\ \cos(t) \end{bmatrix}$$

$$\begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 6 \\ 3 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\therefore c_1 = 6 \quad c_2 = 3$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = 6 \begin{bmatrix} \cos(t) \\ -\sin(t) \end{bmatrix} + 3 \begin{bmatrix} \sin(t) \\ \cos(t) \end{bmatrix}$$