

# Week 11

Systems of differential equations

# 11.1: Converting Systems to Matrix Systems

Systems of differential equations involve multiple interrelated differential equations that describe how several variables change with respect to one another over time.

## Systems of 1st order differential equations

$$x'_1 = a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n + f_1$$

$$x'_n = a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n + f_n$$

$$\frac{dx}{dt} = Ax + f$$

$$\frac{dx}{dt} \begin{bmatrix} x_1 \\ \dots \\ x_n \end{bmatrix} = \begin{bmatrix} A \end{bmatrix} \begin{bmatrix} x_1 \\ \dots \\ x_n \end{bmatrix} \begin{bmatrix} f_1 \\ \dots \\ f_n \end{bmatrix}$$

**Homogeneous:** if  $f = 0$

**Non-homogeneous:** if  $f \neq 0$

## Converting from 2nd order to 1st order systems

$$x'' + p(t)x' + q(t)x = f(t)$$

- $x' = y$

- $y' = -q(t)x - p(t)y + f$

## 11.1.1: 1st Order, Single Variable Example

Convert to an equivalent first order system.

$$y'' + 17y' + 3y = e^x$$

## 11.1.2: 1st Order, Multi-Variable Example

Convert to an equivalent first order system.

$$x'' = x + y$$

$$y'' = 2x - 3y$$

## 11.1.3: 1st to 2nd Order Example

Rewrite the following first-order system into a second-order equation for  $x(t)$ .

$$\begin{aligned}x' &= 3x + 2y \\ y' &= x - y\end{aligned}$$

# 11.2: Systems with Real Eigenvalues

Constant coefficient systems refer to systems of differential equations where the coefficients are constant, making them easier to analyze and solve.

## Real eigenvalues

$$\begin{aligned}x' &= 5x + 3y \\ y' &= 3x + 5y\end{aligned}$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 5 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Solve matrix,  $A$ , to get

$\lambda = 8$  with eigenvector  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $\lambda = 2$  with eigenvector  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$

The solution is then

$$\begin{bmatrix} x \\ y \end{bmatrix} = c_1 e^{8t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$



# 11.2: Systems with Complex Eigenvalues

Constant coefficient systems refer to systems of differential equations where the coefficients are constant, making them easier to analyze and solve.

## Complex eigenvalues

$$\begin{aligned}x' &= 3x + 4y \\ y' &= -4x + 3y\end{aligned}$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ -4 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Solve matrix,  $A$ , to get

$\lambda = 3 \pm 4i$ , then we take the **positive** eigenvalue,  $\lambda = 3 + 4i$

and solve for the eigenvector to get  $\begin{bmatrix} 1 \\ i \end{bmatrix}$

Now, we plug this into the general solution form:

$$\begin{bmatrix} x \\ y \end{bmatrix} = e^{at}(\cos(bt) + i \sin(bt)) [v]$$

where  $\lambda = a \pm bi$ .

So, for this example, we plug in to get

$$\begin{bmatrix} x \\ y \end{bmatrix} = e^{3t}(\cos(4t) + i \sin(4t)) \begin{bmatrix} 1 \\ i \end{bmatrix} = \begin{bmatrix} e^{3t} \cos 4t \\ -e^{3t} \sin 4t \end{bmatrix} + i \begin{bmatrix} e^{3t} \sin 4t \\ e^{3t} \cos 4t \end{bmatrix}$$

The  $i$  gets absorbed into the constants, and our final solution is

$$\begin{bmatrix} x \\ y \end{bmatrix} = c_1 \begin{bmatrix} e^{3t} \cos 4t \\ -e^{3t} \sin 4t \end{bmatrix} + c_2 \begin{bmatrix} e^{3t} \sin 4t \\ e^{3t} \cos 4t \end{bmatrix}$$

## 11.2.1: Real Solution Example

Find the general and specific solutions of the following system.

$$\begin{aligned}x' &= 2x - 3y & x(0) &= 1 \\y' &= -3x + 10y & y(0) &= 4\end{aligned}$$



## 11.2.2: Complex Solution Example

Find the general and specific solutions of the following equation.

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \quad \begin{bmatrix} x(0) \\ y(0) \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$