

Week 12

More complicated systems of differential equations

12.1: Non-Diagonalizable Coefficient Matrices

Derivation of $\mathbf{x} = \mathbf{P}\mathbf{y}$

$$\mathbf{x}' = \mathbf{A}\mathbf{x}$$

$$\mathbf{A} = \mathbf{P}\mathbf{J}\mathbf{P}^{-1}$$

$$\mathbf{x}' = \mathbf{P}\mathbf{J}\mathbf{P}^{-1}\mathbf{x}$$

$$\text{Let } \mathbf{x} = \mathbf{P}\mathbf{y} \rightarrow \mathbf{y} = \mathbf{P}^{-1}\mathbf{x}$$

$$\mathbf{x}' = \mathbf{P}\mathbf{J}(\mathbf{P}^{-1}\mathbf{x})$$

$$\mathbf{P}^{-1}\mathbf{x}' = \mathbf{J}(\mathbf{P}^{-1}\mathbf{x})$$

$$(\mathbf{P}^{-1}\mathbf{x})' = \mathbf{J}(\mathbf{P}^{-1}\mathbf{x})$$

$$\mathbf{y}' = \mathbf{J}\mathbf{y}$$

Solving for \mathbf{y}

4x4 with
one λ

$$\mathbf{y} = c_1 e^{\lambda t} \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + c_2 e^{\lambda t} \begin{bmatrix} t \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_3 e^{\lambda t} \begin{bmatrix} \frac{t^2}{2!} \\ t \\ 1 \\ 0 \end{bmatrix} + c_4 e^{\lambda t} \begin{bmatrix} \frac{t^3}{3!} \\ \frac{t^2}{2!} \\ t \\ 1 \end{bmatrix}$$

4x4 with
2 λ 's

$$\mathbf{y} = c_1 e^{\lambda_1 t} \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + c_2 e^{\lambda_1 t} \begin{bmatrix} t \\ 1 \\ 0 \\ 0 \end{bmatrix} + c_3 e^{\lambda_2 t} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + c_4 e^{\lambda_2 t} \begin{bmatrix} 0 \\ 0 \\ t \\ 1 \end{bmatrix}$$

12.1.1: 2x2 Fundamental Solutions Example

Find the fundamental solutions matrix for the following system.

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

12.2: Non-Homogeneous Systems

Non-homogeneous systems refer to systems of differential equations that include a non-zero external input or forcing function, making the system's behavior more complex.

Method of Undetermined Coefficients

- Make “guess” from f
 - $x = a \cdot v$
- Plug guess in as x into $x' = Ax + f$
- Solve for guess
- $x = x_c + x_p$

When f **does not** overlap x_c

Variation of Parameters

- Solve for x_c
- Find X (x_c as one matrix)

$$x_p = X \int (X^{-1} \times f) dt$$

When f **does** overlap x_c

12.2: Variation of Parameters for 2nd-Order ODEs

- $y'' + p(t)y' + q(t)y = F(t)$
- Solve for y_p given $y_c = y_1 + y_2$

$$y_p = y_1 \int \frac{-y_2 \times F(t)}{W} dt + y_2 \int \frac{y_1 \times F(t)}{W} dt$$

12.2.1: 2x2 Non-Homogenous Example

Find the particular solution for the following system.

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} 3e^t \\ 6e^t \end{bmatrix}$$

12.2.2: 4x4 Non-Homogenous Example

Find the general solution of the following system..

$$\vec{x}'(t) = \begin{bmatrix} -2 & 2 & 0 & 1 \\ 0 & -2 & 0 & 0 \\ 0 & -1 & -2 & -1 \\ 0 & 0 & 0 & -2 \end{bmatrix} \vec{x}(t).$$

$$\text{Hint: } \begin{bmatrix} -2 & 2 & 0 & 1 \\ 0 & -2 & 0 & 0 \\ 0 & -1 & -2 & -1 \\ 0 & 0 & 0 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 1 \\ 0 & -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} -2 & 1 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & -2 & 1 \\ 0 & 0 & 0 & -2 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & 1 \\ 0 & -1 & 0 & 1 \end{bmatrix}^{-1}$$